## DURAPAC

COMPACTION SYSTEMS

# **BIN LIFTERS**

**SPECIALITY RANGE** 







### STANDARD BIN LIFTER

#### **OVERVIEW**

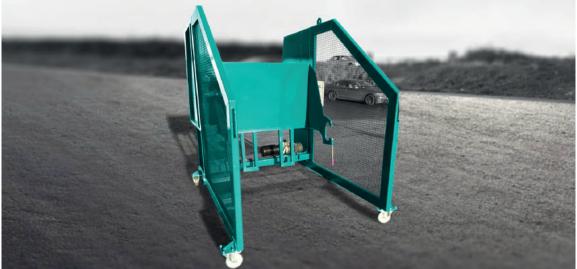
Our standard Bin Lifter tips in over 1450mm off ground – and can be designed to suit a wide range of bins.

There are two typical arrangements for lifting and tipping – the comb style and the trunnion style. The comb style mechanism is designed to pick up the bins from the front lip, whereas the trunnion style lifter picks the bins up by lifting lugs placed on the side of the wheelie bins. Durapac bin lifters can also be designed to interface with dolar bins and specialised cart with optional fork attachments or bucket style lifters also available. Standard Durapac bin lifters are designed to lift a SWL of 450kg, this SWL can be upgraded if required. So regardless of what style of cart, container or bin you need to tip a Durapac Bin Lifter can tip it for you.











#### **OVERVIEW**

Our High Level Bin Lifter tips in over 2400mm to 2650mm off ground – and can be designed to suit a wide range of bins.

Our High Level Bin Lifter tips in over 2400mm to 2650mm off ground – and can be designed to suit a wide range of bins. Like our standard bin lifter it can be fitted out with either a comb style lifter or a trunnion style lifter. Available with a full surround interlocked safety cage or with side screens for operator safety the Durapac high level bin lifter is your trusted unit for lifting and tipping.













#### **OVERVIEW**

#### Durapac are world leaders in Bin Lifter design and development.

Durapac have developed various specialised bin lifters to tip in excess of 4m high. These are gear box driven systems which can take the required bins or containers up several levels in one smooth fast action and tip fully into the awaiting reception container. Traversing options are also available where the Bin Lifter can travel sideways across a defined range to tip into large reception vehicles. Durapac Bin Lifters can be designed to suit your exact requirements.



